### **Optimal Power Flow for Microgrids with Faulty Generators**

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The 9<sup>th</sup> International Conference on Power and Energy Systems December 10, 2019





# **Microgrids and its operation**





Source: US energy information administration Reported in the Annual Energy Outlook 2013



# **Microgrids and its operation**





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### **Operation of Microgrids**





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### **Operation of Microgrids**





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### **Generator faults matters**







Short in slot section



Short-circuit in stator windings



Difficult to maintain individual generators in microgrids

#### Image sources

Alewine, Kevin. "Wind Turbine Generator Failure Modes." Shermco Industries (2011). PUNCH, Power failure: Nigerians burn N17.5tn on generators in five years





Source: Seinsch, H. O. "Monitoring und diagnose elektrischer maschinen und antriebe." *Proc. VDE Workshop.* 2001.



### In this study, we want to answer...

How does the slight fault influences the power generation?





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Is it possible to connect the fault detection methods to the optimal power flow?





How does the slight fault influences the power generation?

Is it possible to connect the fault detection methods to the optimal power flow?

How can the MSO operate the microgrid in cost-optimal way in faulty-generator scenario?





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Case study

### Conclusion





# **Optimal power flow**

Original OPF → Function of healthy generators  $\min \sum_{i \in \mathcal{N}} C_i (P_{G_i})$ subject to  $P_{G_i,min} \leq P_{G_i} \leq P_{G_i,max}$   $Q_{G_i,min} \leq Q_{G_i} \leq Q_{G_i,max}$   $V_{i,min} \leq V_i \leq V_{i,max}$   $P_i + jQ_i = V_i I_i^*$ where

$$P_i = P_{G_i} - P_{L,i}$$
$$Q_i = Q_{G_i} - Q_{L,i}$$





# **Optimal power flow**

Original OPF  $\rightarrow$  Function of healthy generators  $\min \sum_{i \in \mathcal{N}} C_i (P_{G_i})$ subject to  $P_{G_i,min} \leq P_{G_i} \leq P_{G_i,max}$   $Q_{G_i,min} \leq Q_{G_i} \leq Q_{G_i,max}$   $V_{i,min} \leq V_i \leq V_{i,max}$   $P_i + jQ_i = V_i I_i^*$ where

 $P_i = P_{G_i} - P_{L,i}$  $Q_i = Q_{G_i} - Q_{L,i}$ 

Optimal power flow in faulty-generator scenario
→ Function of heathy and faulty generators

 $\min \sum_{i \in \mathcal{N}} \widetilde{\boldsymbol{C}}_{i} (\boldsymbol{P}_{\boldsymbol{G}_{i}})$ 

subject to

 $P_{G_{i},min} \leq P_{G_{i}} \leq P_{G_{i},max}$   $Q_{G_{i},min} \leq Q_{G_{i}} \leq Q_{G_{i},max}$   $V_{i,min} \leq V_{i} \leq V_{i,max}$   $P_{i} + jQ_{i} = V_{i}I_{i}^{*}$ 

where

$$P_i = P_{G_i} - P_{L,i}$$
$$Q_i = Q_{G_i} - Q_{L,i}$$



# **Effect of incipient fault**

### Inter-turn short circuit fault in stator windings





$$S(\%) = \frac{|\mu_{abc}i_f|}{\sqrt{2} I_{rms}}, \quad \mu_{abc} = \begin{bmatrix} \mu_a \\ \mu_b \\ \mu_c \end{bmatrix}$$

S: severity factor

De Angelo, Cristian H., et al. "Online model-based stator-fault detection and identification in induction motors." *IEEE Transactions on Industrial Electronics* 56.11 (2009): 4671-4680.





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# **Effect of incipient fault**



TABLE I				
OPERATION CONDITIONS				

Rated power $p_{nom}$ 50 kWRated voltage $V_{nom}$ 400 VNumber of pole pairsP2Stator resistance $R_s$ 0.2448 $\Omega$ Rotor resistance $R_r$ 0.4847 $\Omega$ Stator inductance $L_s$ 80.76 mHRotor inductance $L_r$ 82.12 mHMutual inductance $L_m$ 77.2 mHIG inertiaJ0.1 kg/m²	Characteristic	Symbol	Value
Grid normal frequency $f_e$ 50 Hz	Rated power Rated voltage Number of pole pairs Stator resistance Rotor resistance Stator inductance Rotor inductance Mutual inductance IG inertia Grid normal frequency	$p_{nom}$ $V_{nom}$ $P$ $R_s$ $R_r$ $L_s$ $L_r$ $L_m$ $J$ $f_e$	50 kW 400 V 2 0.2448 Ω 0.4847 Ω 80.76 mH 82.12 mH 77.2 mH 0.1 kg/m <sup>2</sup> 50 Hz

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### **OPF as a function of severity factor**







 $P_{G,i} = \alpha_i(P_{G_f,i}, \mathbf{S}_i)$ 



### **OPF as a function of severity factor**



$$P_{G,i} = \alpha_i(P_{G_f,i}, \mathbf{S}_i)$$

$$\alpha_i \left( P_{G_f,i}, \mathbf{S}_i \right) \approx P_{G_f,i} \left( a_{1,i} + a_{2,i} \mathbf{S}_i + a_{3,i} \mathbf{S}_i^2 \right)$$

Polynomial approximation





# **OPF** as a function of severity factor



$$P_{G,i} = \alpha_i(P_{G_f,i}, \mathbf{S}_i)$$

$$\alpha_i \left( P_{G_f,i}, \mathbf{S}_i \right) \approx P_{G_f,i} \left( a_{1,i} + a_{2,i} \mathbf{S}_i + a_{3,i} \mathbf{S}_i^2 \right)$$

Polynomial approximation

Optimal power flow

→ Function of the power of heathy/ faulty generators and its severity

 $\min \sum_{i \in \mathcal{N}} C_i (P_{G_i}, S_i)$ 

subject to

 $P_{G_{i},min}(\mathbf{S}_{i}) \leq P_{G_{i}} \leq P_{G_{i},max}(\mathbf{S}_{i})$  $Q_{G_{i},min}(\mathbf{S}_{i}) \leq Q_{G_{i}} \leq Q_{G_{i},max}(\mathbf{S}_{i})$  $V_{i,min} \leq V_{i} \leq V_{i,max}$  $P_{i} + jQ_{i} = V_{i}I_{i}^{*}$ 













Current, voltage, speed sensors

De Angelo, Cristian H., et al. "Online model-based stator-fault detection and identification in induction motors." *IEEE Transactions on Industrial Electronics* 56.11 (2009): 4671-4680.







#### Current, voltage, speed sensors

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### **Case Study**

### 10 node Microgrid

![](_page_22_Figure_2.jpeg)

**O** Nodes

#### Simulation parameters

Line impedance:  $Z_{mn} = 0.4576 + j1.078$ 

Coefficients for quadratic generation cost  $c_{2,i} = 200, c_{1,i} = 40, c_{0,i} = 1, i \in \{1,5,7,10\}$ 

Generation power limits of healthy generators  $P_{\min,i} = 5$  kW,  $P_{\max,i} = 50$  kW

Active/Reactive power Load at each node

![](_page_22_Figure_9.jpeg)

![](_page_22_Picture_10.jpeg)

# **Comparison of total costs against original OPF**

### 10 node Microgrid

![](_page_23_Figure_2.jpeg)

\$/hr

![](_page_23_Figure_4.jpeg)

■ O OPF ■ P OPF

Faulty generator at node 5

![](_page_23_Picture_6.jpeg)

## **Power dispatches with generator fault at node 5**

![](_page_24_Figure_1.jpeg)

![](_page_24_Picture_2.jpeg)

![](_page_24_Picture_4.jpeg)

Concerned the tertiary control of microgrids in a faulty-generator scenario

![](_page_25_Picture_3.jpeg)

![](_page_25_Picture_4.jpeg)

Concerned the tertiary control of microgrids in a faulty-generator scenario

Investigated how the inter-turn short circuit fault affects to power generation

![](_page_26_Picture_3.jpeg)

![](_page_26_Picture_4.jpeg)

Concerned the tertiary control of microgrids in a faulty-generator scenario

Investigated how the inter-turn short circuit fault affects to power generation

The optimal power flow problem in a faulty-faulty generator scenario is formulated as a function of generation of faulty generators and its severity factor

![](_page_27_Picture_4.jpeg)

![](_page_27_Picture_5.jpeg)

Concerned the tertiary control of microgrids in a faulty-generator scenario

Investigated how the inter-turn short circuit fault affects to power generation

- The optimal power flow problem in a faulty-faulty generator scenario is formulated as a function of generation of faulty generators and its severity factor
- The proposed optimal power flow algorithm provides less operation cost compared to the original one in faulty-generator scenario

![](_page_28_Picture_5.jpeg)

![](_page_28_Picture_6.jpeg)

# Thank you for listening! Q&A

![](_page_29_Picture_1.jpeg)

![](_page_29_Picture_2.jpeg)

# **Diesel and induction generator**

Direct Current Microgrid Power Modeling and Control Manuela Sechilariu, Fabrice Locment, in <u>Urban DC</u> <u>Microgrid</u>, 2016 3.6 Diesel Generator Operating Mode Modeling The diesel generator is used as a backup source only in the off-grid mode of the <u>DC microgrid</u>.

### https://homesteady.com/how-12055415make-own-3phase-converter.html

### Energizing Renewable Energy Systems and Distribution Generation

T. Adefarati, R.C. Bansal, in Pathways to a Smarter Power System, 2019

#### 2.4.3 Diesel Generator

Diesel generators can be utilized as standalone, emergency, standby, and peak shaving units because of the following characteristics: availability, quick start up, reliability, fast ramp up, durability, etc. [8]. The diesel generators have high operating cost and generate electricity on demand when compared with renewable DERs.

# How to Use a Three Phase Induction Motor as a Generator

By Pauline Gill Updated September 26, 2017

Three-phase induction motors are plentiful and relatively inexpensive new or used because of their extensive implementation throughout industry. There are several methods for using them as generators, which vary greatly in complexity and advisability for the do-it-yourselfer. The best practical approach is to wire it as you would for a normal motor application, and then to over-run it while it is operating—with an engine, windmill, or turbine to reverse current flow and push power back into the grid. This practice effectively slows the demand meter. Wind Turbine Components and Descriptions R. Nolan Clark, in Small Wind, 2014 Synchronous generators are not normally used on small <u>wind</u> <u>machines</u> because of the additional equipment needed to make them operate efficiently.

![](_page_30_Picture_11.jpeg)

![](_page_30_Picture_12.jpeg)

### References

### Image sources

http://engineering.electrical-equipment.org/electricaldistribution/electric-load-forecasting-advantages-challenges.html

![](_page_31_Picture_3.jpeg)

![](_page_31_Picture_4.jpeg)

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![](_page_32_Picture_22.jpeg)

![](_page_32_Picture_23.jpeg)

### **Generator faults matters**

![](_page_33_Figure_1.jpeg)